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Occlusion over ear surfaces results in performance degradation of ear registration and recognition systems. In this paper, we propose an occlusion-resistant three-dimensional (3D) ear recognition system consisting of four primary components: (1) an ear detection component, (2) a local feature extraction and matching component, (3) a holistic matching component, and (4) a decision-level fusion algorithm. The proposed approach uses a 3D range image for automatic ear recognition and coregistered 2D ear images for automatic detection. To robustly recognize the ear, the proposed technique uses a proposed two-step NGT-based matching method that generates a correspondence that maintains a rigid constraint. Gesture recognition: To assess the spatial resolution of the augmented vision, the experimenter stood 1.2 m from the participants and made one of six gestures with their right hand held to their side (thumb-up, shaka [“hang loose”], open palm, fist, peace sign, okay). The participants mirrored the hand gesture and indicated their confidence. Participants 1, 2, and 3 were able to complete the person localization task consistently both with and without augmented reality and reported high confidence (Fig. 4A). Participant 3 (brown bars) indicated after the task that the augmentation made her more confident (despite her ratings being similar).

This paper introduces an improved ear recognition approach based on 3 dimensional keypoint matching and combining local and holistic features. At first, the 3D keypoints are detected using the shape index image. The system consists of four primary steps: i) ear image segmentation; ii) local feature extraction and matching; iii) holistic feature extraction and matching; and iv) combination of local and holistic features at the match score level. Ear biometrics using 2D and 3D images, 2005 IEEE Computer Society Conference on Computer Vision and Pattern Recognition (CVPR'05) - Workshops, page 121, 2005. P. Yan and K. W. Bowyer. Ear Biometrics in 2D and 3D "Localization and Recognition (Augmented Vision and Reality). Original price : 109 \$ Site price : 4 \$. Author There are two types of characteristics used in biometrics for person authentication. The first type of characteristics are physiological in nature, while the other is based on the behavior of human beings. Common examples of physiological biometric traits are face, ear, iris, fingerprint, hand geometry, hand vein pattern, palm print, etc., whereas signature, gait (walking pattern), speech, key strokes dynamics, etc., are examples of behavioral biometrics. Download WordPress Themes. Download WordPress Themes. For the augmented reality scene we need to render pictures of real world - video coming from camera, file or any other source and containing some optical glyphs to recognize. Without going into video acquisition/reading details, we can just assume that every new video frame is provided as .NET's Bitmap. In 3D augmented reality this would be even worse, since a small change in few pixels will lead to a bit different estimation of 3D pose, which will make 3D model to shake even more. To eliminate the above described noise in corners detection leading to AR model shaking, it is possible to implement glyphs' coordinates tracking.